Waveform fitting

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Typical waveform of neutron detector by position

- Normalize waveform with its area and move in x(time).
- Get typical waveform from 2D histogram's profile.



hisWave_0_0_0

Typical waveforms by position



Can we describe waveforms with some function?

Neutron detector waveform fitting



• Fitting with two function

- Make typical waveform by 5 cm width.(41 waveforms for single channel)
- Looks good, some wave did not fit well.
- Fitting is affected small components at 20~50 ns region.
- The components changes by hit position.
- But timing is same.
- Additional wave from light reflected two times? (4.x m difference)

New fitting function ver. 2 $H \times \{f(x,t,\sigma_r,\sigma_d) + h'f(x,t+t_d,\sigma'_r,\sigma'_d)\}$ $+H' \times \{f(x,t+t_4,\sigma_r+\Delta,\sigma_d+\Delta) + h'f(x,t+t_4,\sigma_r+\Delta,\sigma_d+\Delta)\}$



Fitting parameter distributions by x (120 modules)



6

Fitting function ver. 3

Change Δ as function of delayed time (= Wave packet spreads by spread length).

$$\begin{split} H \times & \{f(x,t,\sigma_r,\sigma_d) + h'f(x,t+t_d,\sigma_r',\sigma_d')\} \\ & + H' \times \{f(x,t+t_4,\sigma_r+\Delta \times t_4,\sigma_d+\Delta \times t_4) \\ & + h'f(x,t+t_d+t_4,\sigma_r+\Delta \times (t_d+t_4),\sigma_d+\Delta \times (t_d+t_4))\} \end{split}$$

$$f(x, t, \sigma_r, \sigma_d) \coloneqq \left(1 + \operatorname{erf}\left(\frac{x-t}{\sigma_r}\right)\right) \exp(-\frac{x-t}{\sigma_d})$$

For further analysis, some parameters were modified. H' -> H*Attenuation(t_d)*(reflectivity) h' -> H*Attenuation(t_d+t_4)*(reflectivity)(reflectivity)

```
const Double t AttbyTime = 33.451417;
Double t f8( Double t *x, Double t *p ){
  Double t AttRef = TMath::Exp(-p[6]/AttbyTime );
  Double t Att4m = TMath::Exp(-p[9]/AttbyTime );
  Double t value = p[0]
                                 (TMath::Erf((x[0]-p[2]
   + p[1]*
                                                                                             )) +1 )*TMath::Exp(-(x[0]-p[2]
                                                                  )/(p[3]
                                                                                                                                     )/p[4] )
                                                                                                                                                                 // Primary
   + p[1]*p[5]*AttRef*
                                 (TMath::Erf((x[0]-p[2]-p[6]
                                                                  )/(p[3]+p[7]*p[6]
                                                                                             )) +1 )*TMath::Exp(-(x[0]-p[2]-p[6]
                                                                                                                                     )/(p[4]+p[8]*p[6])) // Secondary
   + p[1]*p[5]*p[5]*Att4m*
                                  (TMath::Erf((x[0]-p[2]-p[9]
                                                                  )/(p[3]+p[7]*p[9]
                                                                                             )) +1 )*TMath::Exp(-(x[0]-p[2]-p[9]
                                                                                                                                     )/(p[4]+p[8]*p[9])) // 4m delay, Primary
   + p[1]*p[5]*p[5]*Att4m*AttRef*(TMath::Erf((x[0]-p[2]-p[6]-p[9])/(p[3]+p[7]*(p[6]+p[9]
                                                                                            ))) +1 )*TMath::Exp(-(x[0]-p[2]-p[6]-p[9])/(p[4]+p[8]*(p[6]+p[9])));// 4m delay, Secondary
  return value;
}
```



Fitting results(1) – Height & Reflectivity



Fitting result(2) - Timing



🔂 c1

 \times

Fitting result(3) – Timing delay & Rising Slope



Fitting with pol1. F(x) = 15.18 - 13.21xF(1) = 1.93 ns ->Offset by light guide X axis : Propagation time Y axis : Rising slope of function Red dots : Rising slope of Primary Blue dots : Rising slope of Secondary