

# Report on KOTO EMCal Study

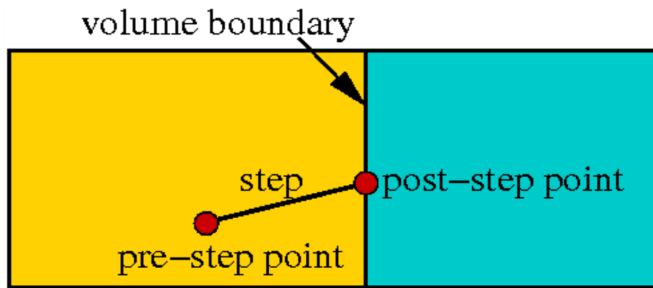
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# Github for Simulation

- ▶ `https://github.com/kyj0118/work`
- ▶ `git clone https://github.com/kyj0118/work`
  - ▶ To download the code
- ▶ Note that
  - ▶ Current CMake only available on Linux.

## Hit definition in the simulation



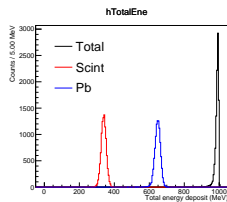
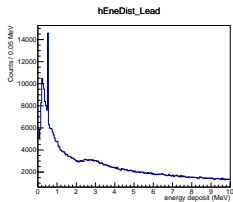
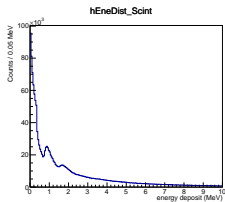
- ▶ Each step has two end-points
  - ▶ Energy deposit during the step =  $e_i$
  - ▶ Hit position and time of the **step** are defined as

$$x_i = \frac{x_i^{\text{pre}} + x_i^{\text{post}}}{2}$$

- ▶ Hit position and time of the **detector** are defined as

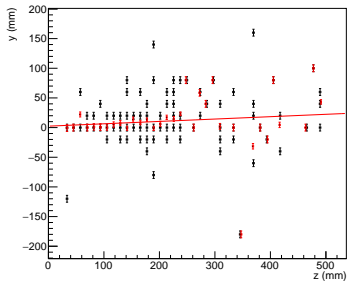
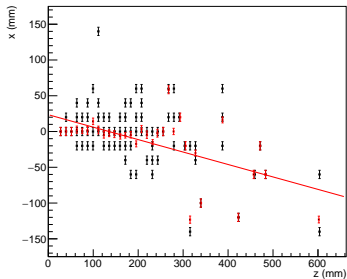
$$x = \frac{\sum_i x_i e_i}{\sum_i e_i} \quad (\text{current GEANT4 output})$$

# energy distribution



► Beam direction as  $(0, 0, 1)$

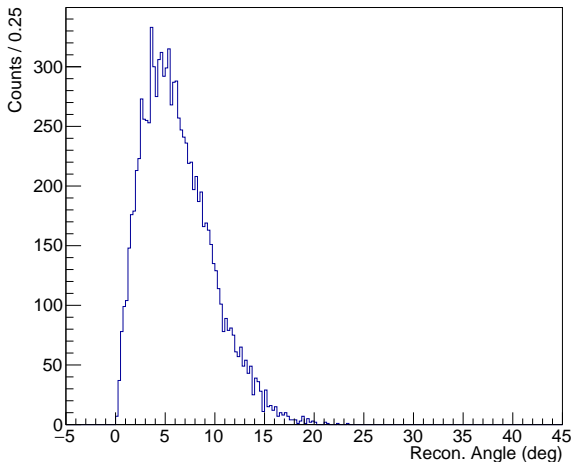
# Tracking(revisited)



- ▶  $x_{\text{mean}} = \frac{\sum_s x_s e_s}{\sum_s e_s}$  energy weighted average over segments in a given layer.
  - ▶ Black  $\rightarrow$  Red
- ▶ Only geometric intrinsic uncertainty considered.

# Reconstructed angle

hSlope\_proc1



►  $\theta = \text{atan}(\Delta z / \sqrt{\Delta x^2 + \Delta y^2})$

# Outlook

- ▶ Check timing distribution
- ▶ Consider energy weighted uncertainty
- ▶ Usage of time difference?