

Current Status of SpiRIT-TPC Tracking

이정우
2016.7.5

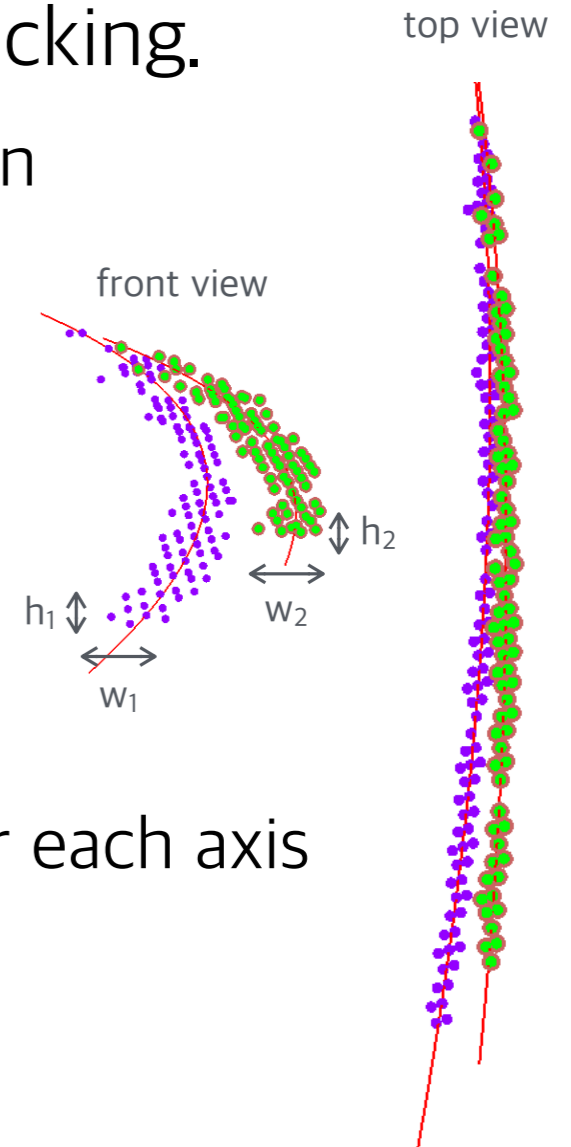
What happened to Tracking

- First algorithm of track finding was taken from FOPIROOT(FOPI software); [Riemann Tracking](#).
- Pros and cons of using Riemann tracking
 - **pros**: Save development time by using approved(?) software.
 - **cons**: Risk coming from property difference of FOPI-TPC and SpiRIT-TPC had to be taken.
- What is needed to use Riemann Tracking? [Hit-Clusters](#).

What happened to Tracking

Hit Clustering

- Why hit-cluster has to be given to Riemann tracking.
 1. In proximity correlator, only the distance between hit-track is compared to **constant cut value**.
 2. For non-clustered hits, distribution sigma for
 - a) dispersion-axis (**width**) and
 - b) perpendicular-axis (**height**) are different.
- Need of pre-tracking: Curve tracking
 1. Two axis, **width** and **height** are divided. Sigma for each axis are caculated to used as cut value.
 2. Not qualitative for full track finding.
 3. Built for hit-clustering.



What happened to Tracking

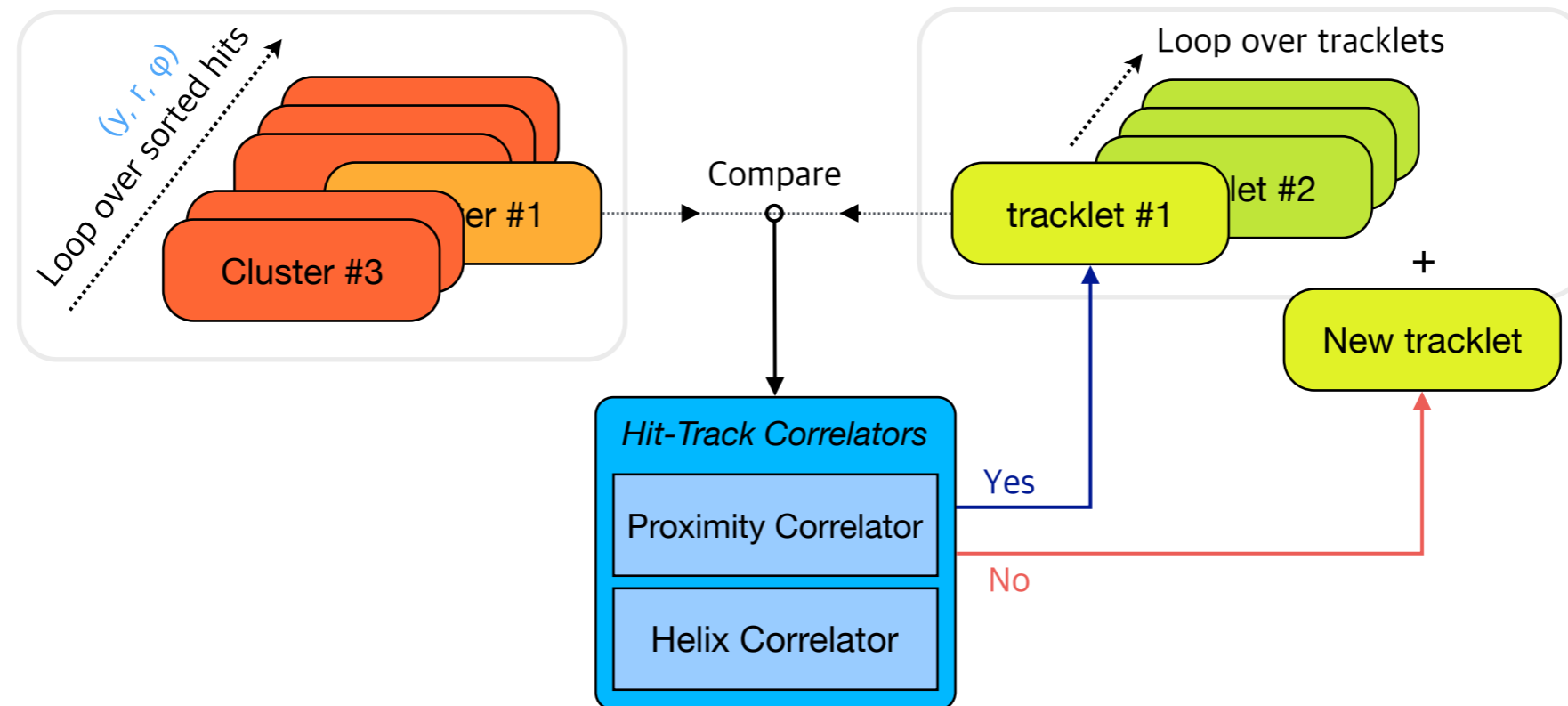
Riemann Tracking



- Fast(non-iterative) and accurate circle fit, using Riemann sphere mapping.

What happened to Tracking

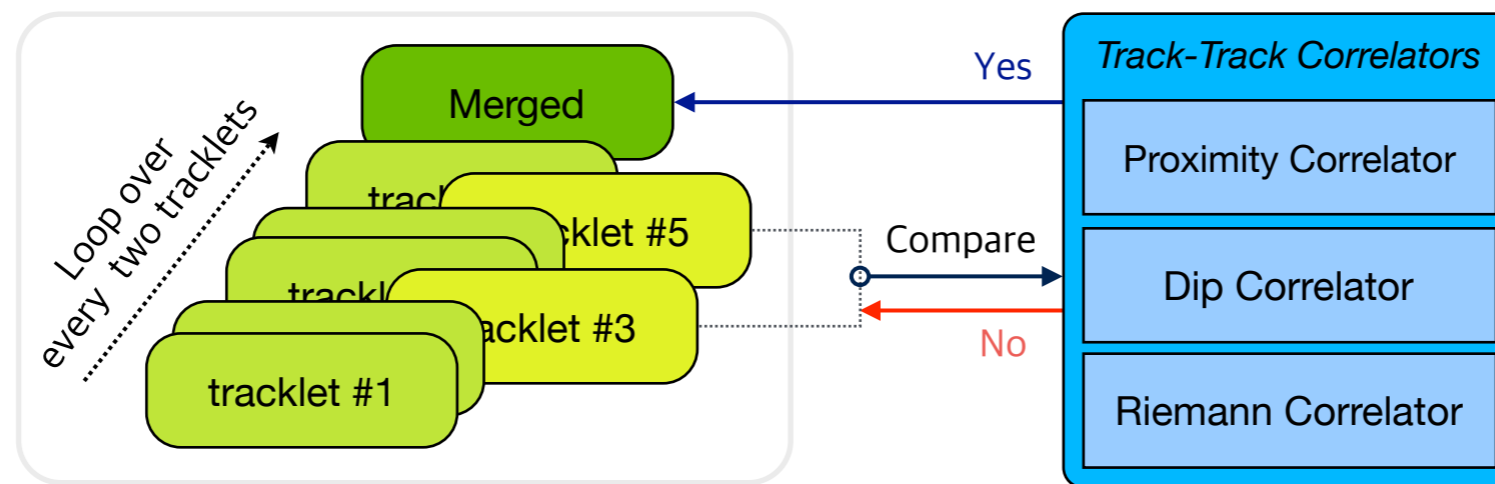
Riemann Tracking



- Hit belong to one track cannot belong to other track.
- Hard to distinguish fake/stable track while building tracks simultaneously.
- Broken tracks are not avoidable.

What happened to Tracking

Riemann Tracking



- In ideal situation, tracklets from one physical track should be merged. But reality is different.
- Many times, following effects make trouble
 - **Bad position resolution** (caused by saturation)
 - **Bad circle fit** (coming from fixed position of Riemann sphere)
 - **Bad clustering** (my fault)

Summary until now

- **Untill now**

1. We tried to use Riemann tracking
2. Curve tracking was developed for clustering
3. Broken tracks are not avoidable.

- **Problems**

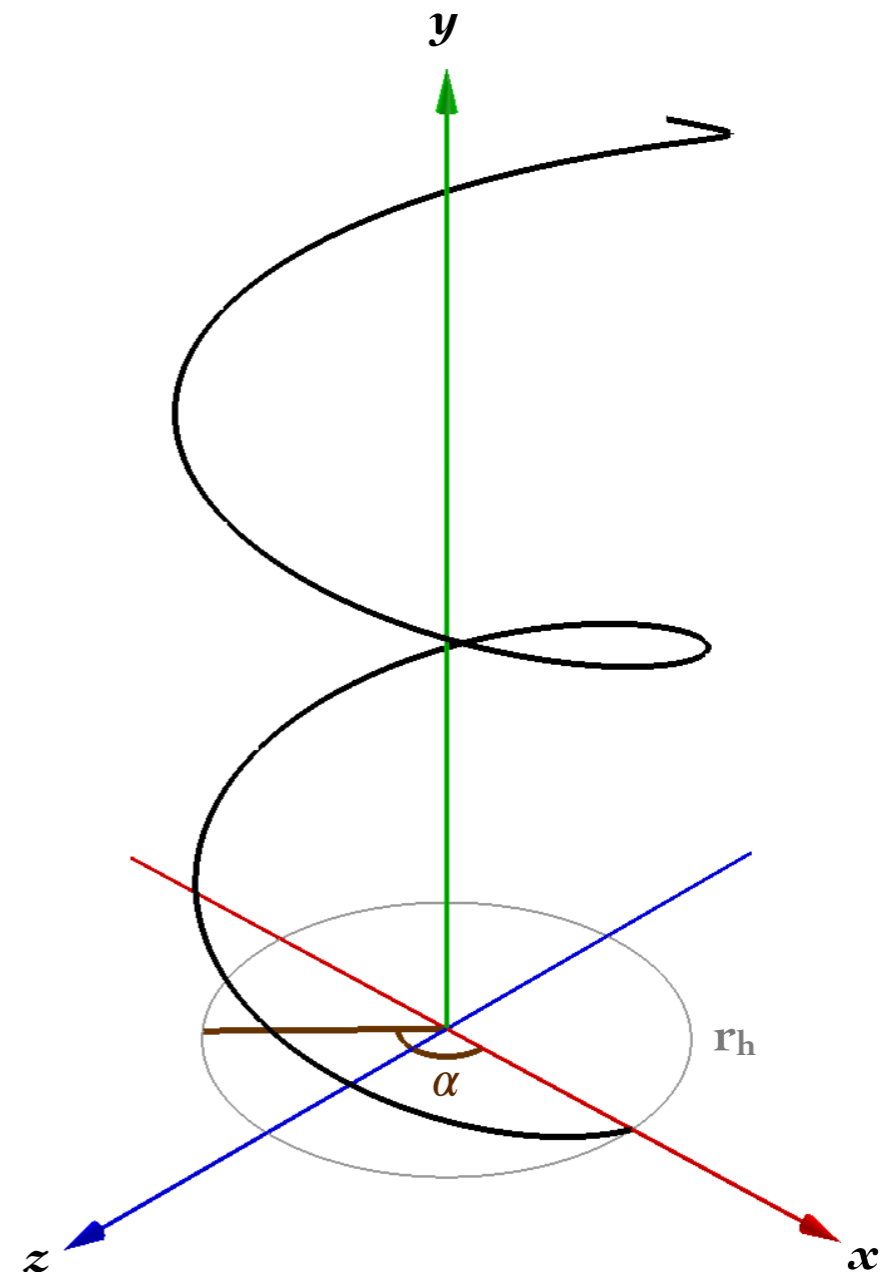
1. Dense system
2. Bad position resolution (saturation)
3. Parameterization of Riemann tracking.

- **What we learned**

1. Riemann fit (circle fit) including possibility of improvement.
2. Advantage of width and height axis.

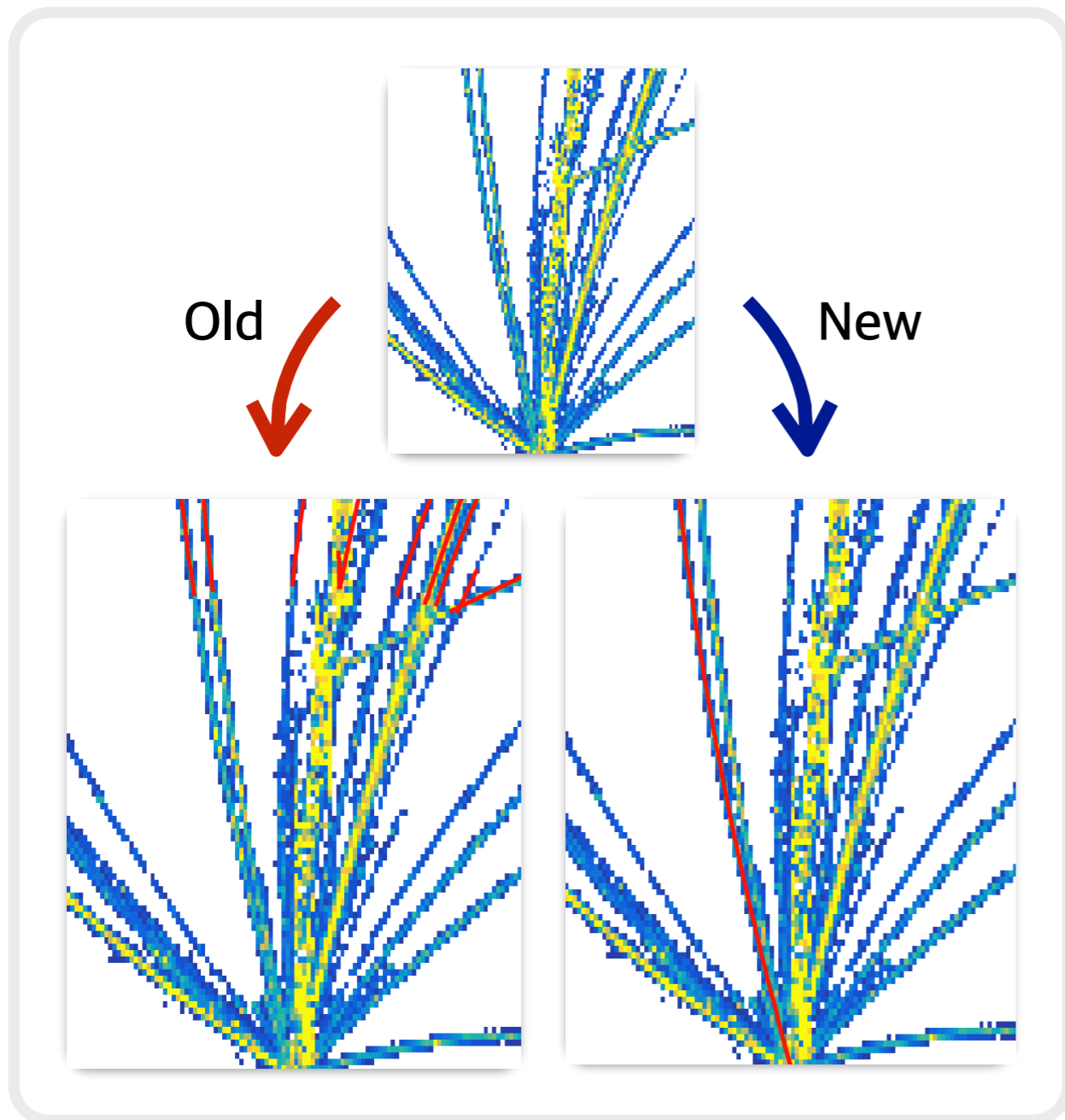
Helix Tracking

- Full control of the code.
- Build full track one by one.
- Helix to straight line map.
- Use advantage of width of the track coming from electron dispersion.
- Use self-update parameters.
 - Riemann sphere position and radius.
 - Proximity cut.
- Deal with shared hit.
- Clustering for Genfit.



Helix Tracking

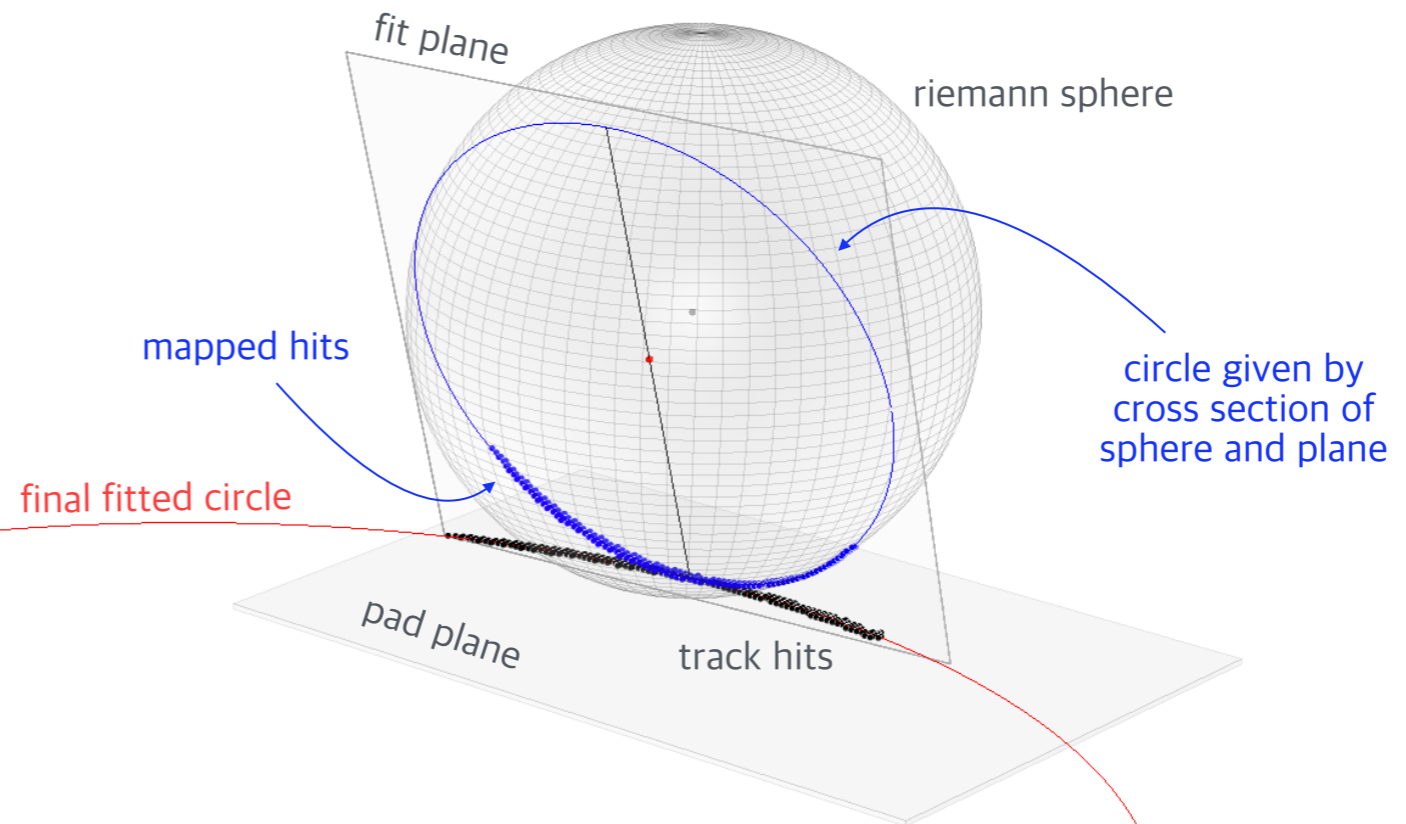
Event Map



- One to one 2D mapping from $\text{pad}(\text{row}, \text{layer})$ to pad hits.
- This enables one to build one full track before another track is built.
- New possibility of finding hits and continue building track from extrapolated position using event map.
- Used hits are left in the event map so other tracks also have chance to check the correlation.

Helix Tracking

Improvement of Riemann Fit

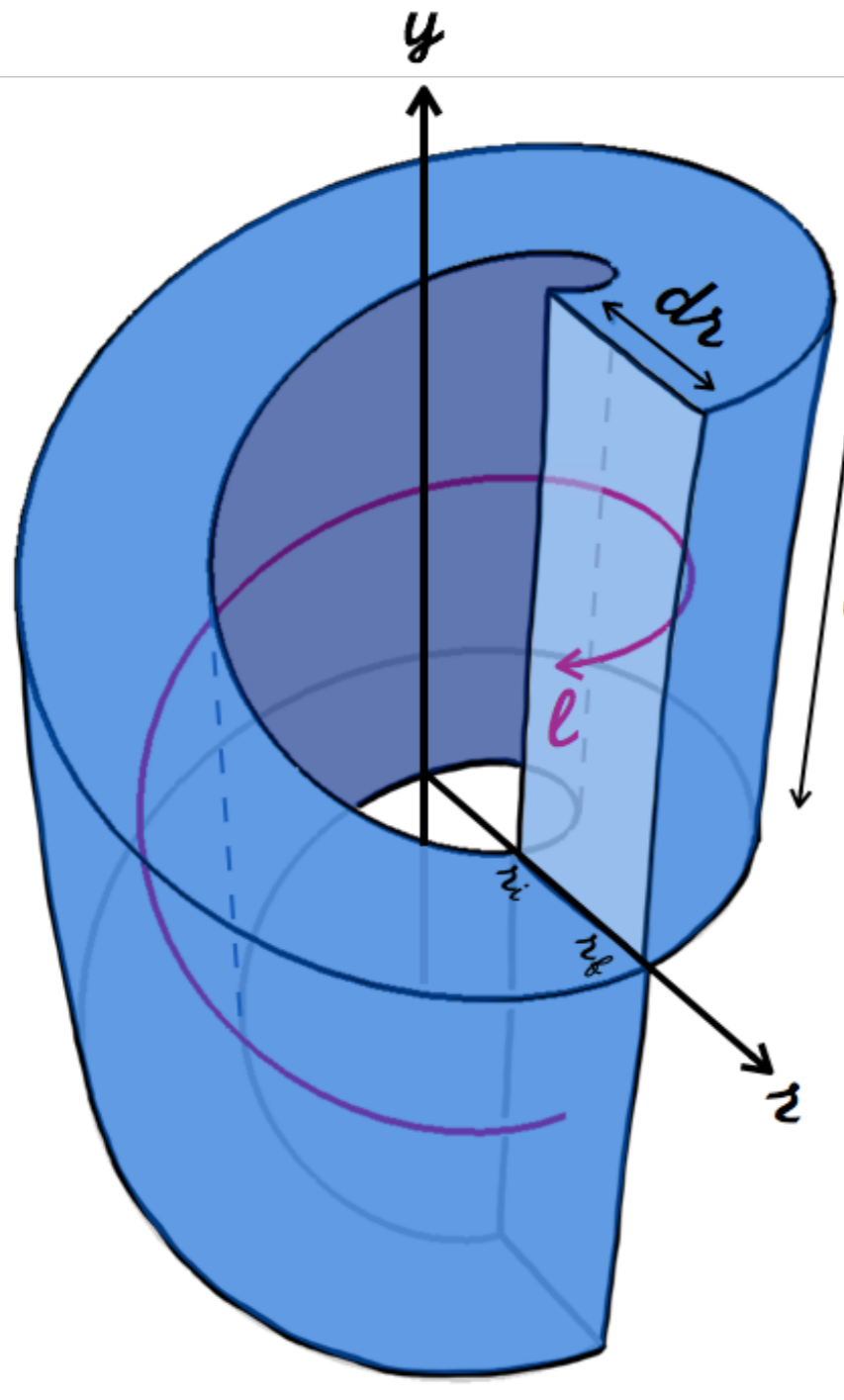


- Fit quality also depend on Riemann sphere center position and radius.
- Center position is choosen from the centroid of the track hits.
 - This also take advantage of determining straight line before the calculation falls into singularity.
- Radius is calculated from the sigma of track hit distribution.

Hit-Track Correlation

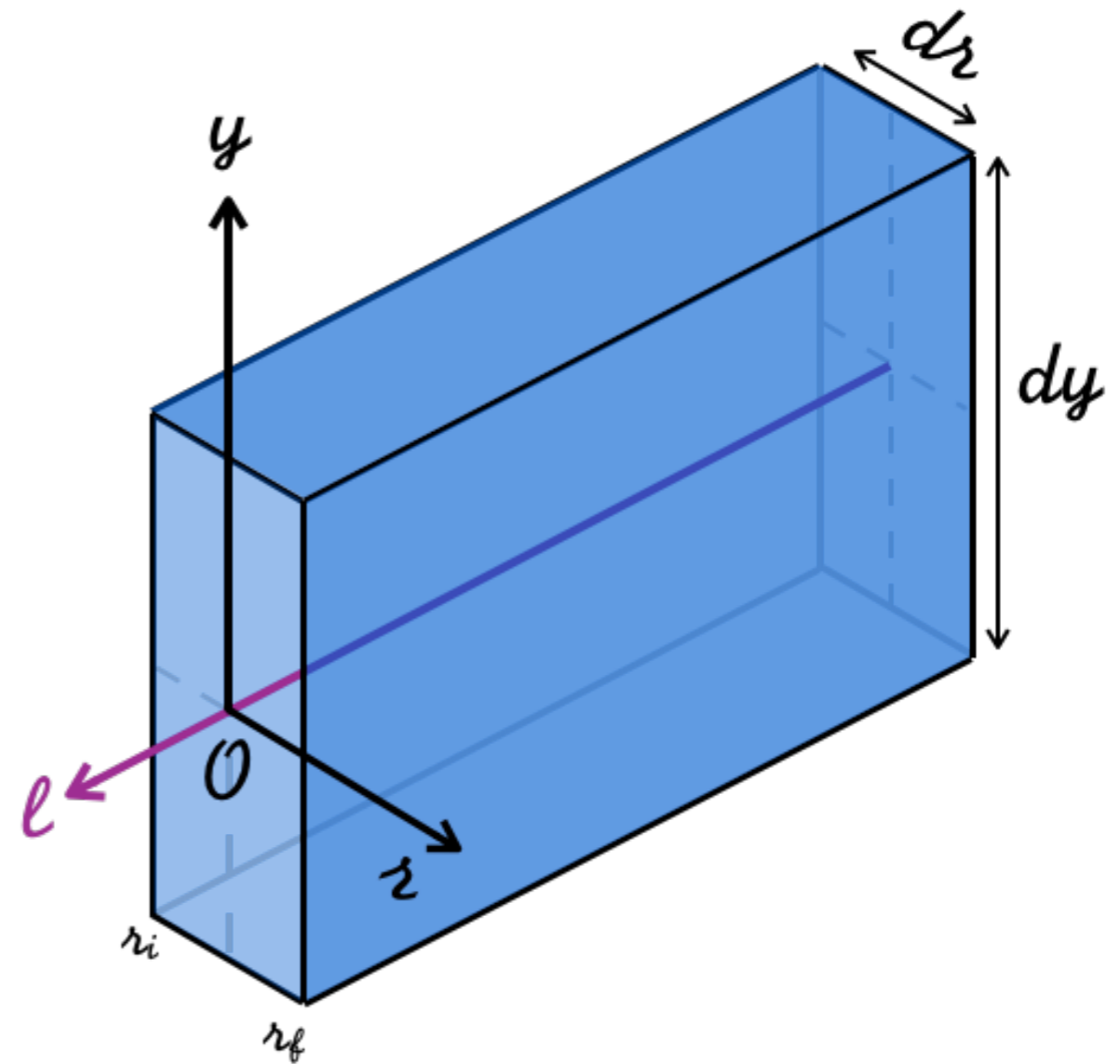
- The only correlation used in track finding is the [shortest distance from point to helix] from two-axis in plane, perpendicular to track propagation direction.
- Distance from point to helix is known as numerical problem, equivalent to solving Kepler's equation using Newton's method.
 - Computing the distance from a point to a helix and solving Kepler's equation - Nuclear Instruments and Methods in Physics Research A 598 (2009) 788-794
- Rather than choosing numerical method, the problem chosen to solving [shortest distance from point to straight line].

Real Space



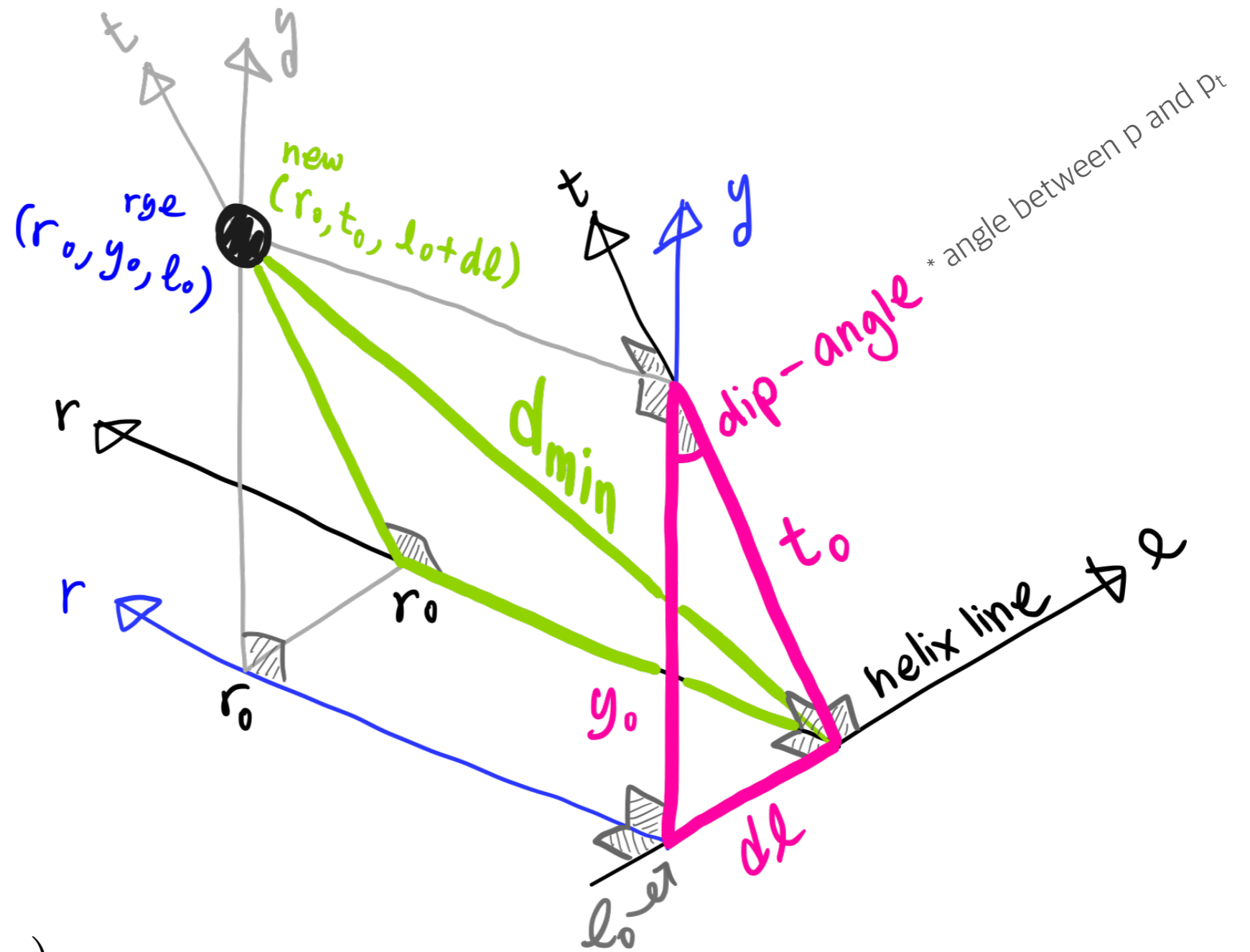
$$0 < \alpha < \pi$$
$$r_i < r < r_f$$

Mapped Space



* y -length of helix propagated in one period,

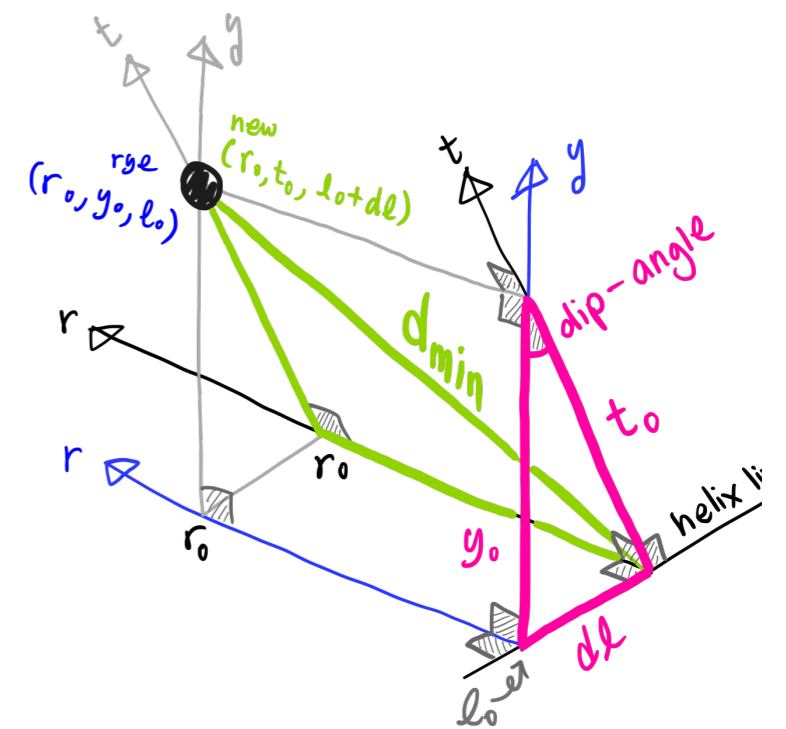
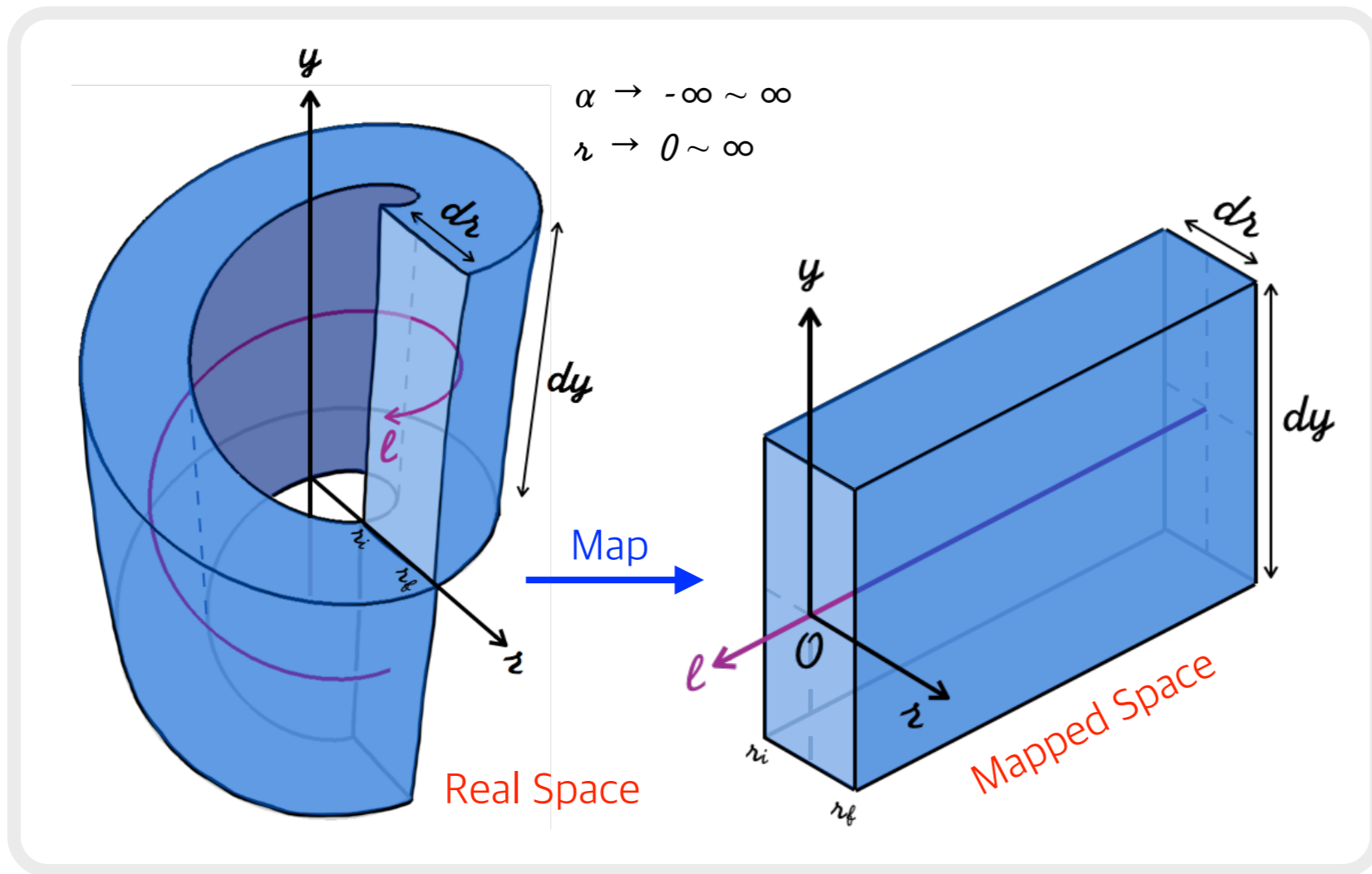




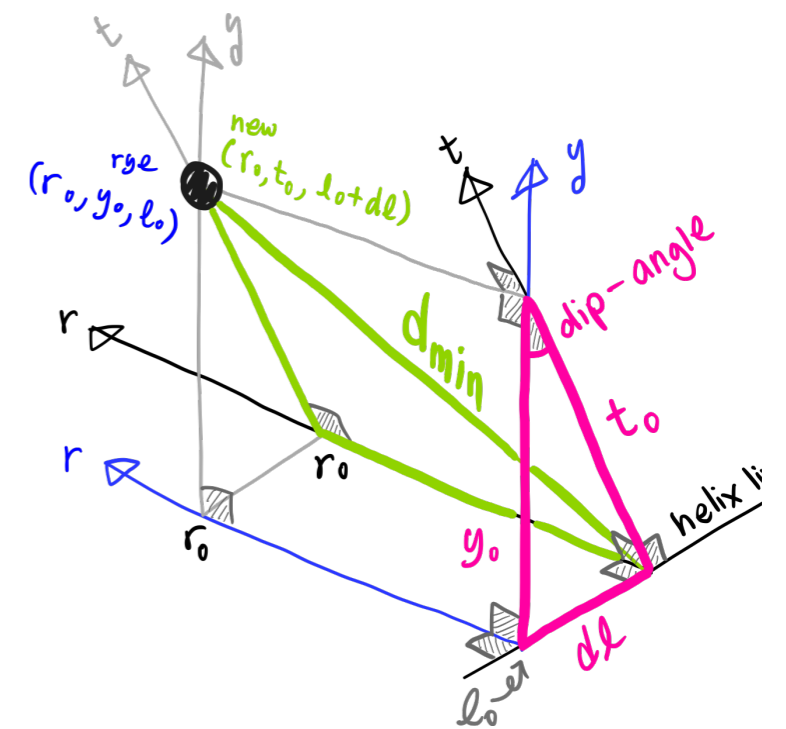
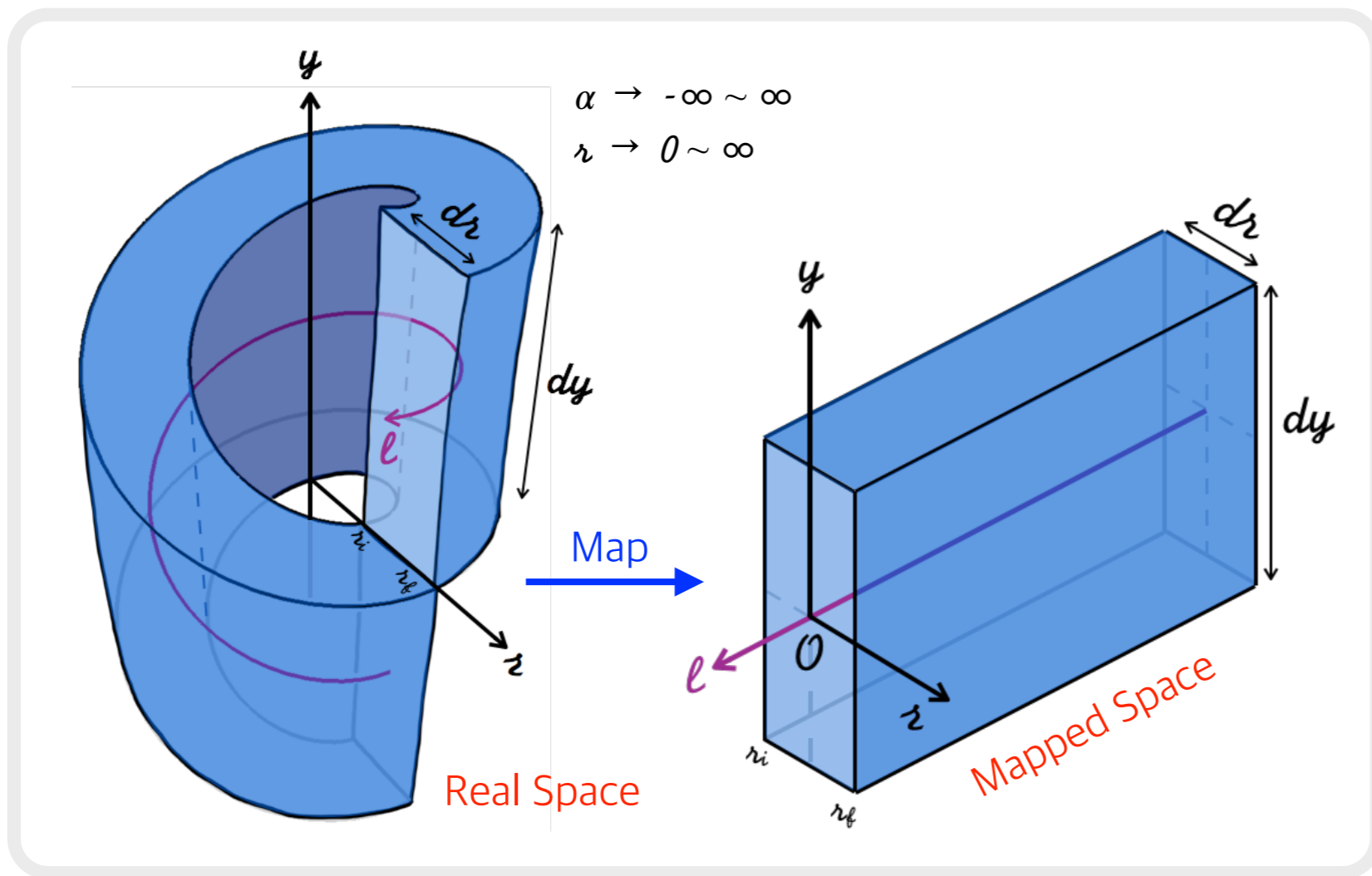
$$r' = r_0$$

$$t' = y_0 \cos(dip)$$

$$l' = l_0 + helicity \times y_0 \sin(dip)$$

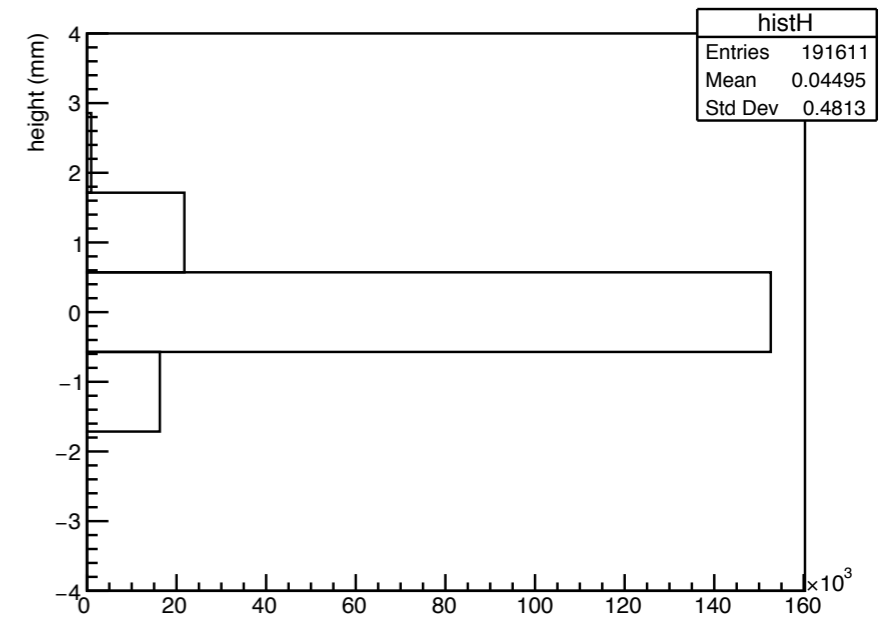
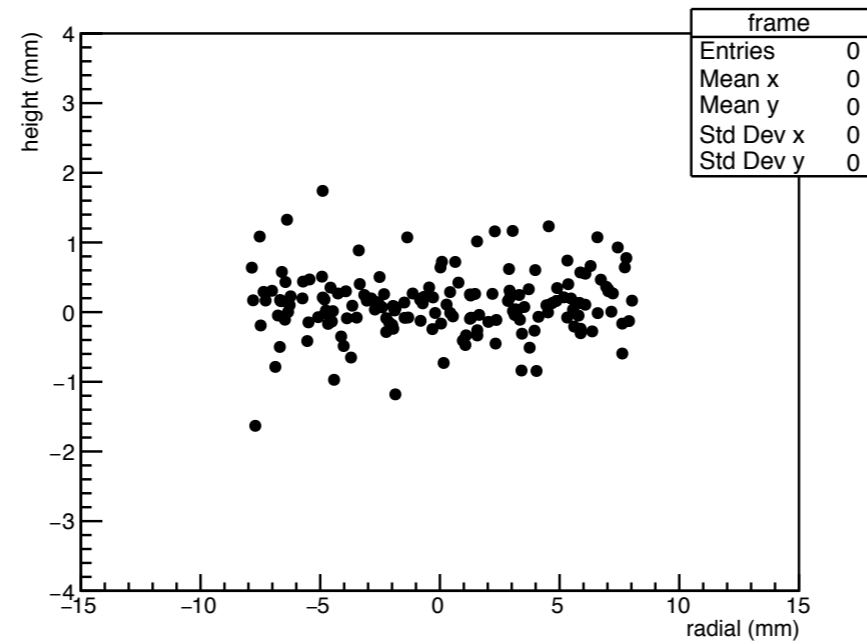
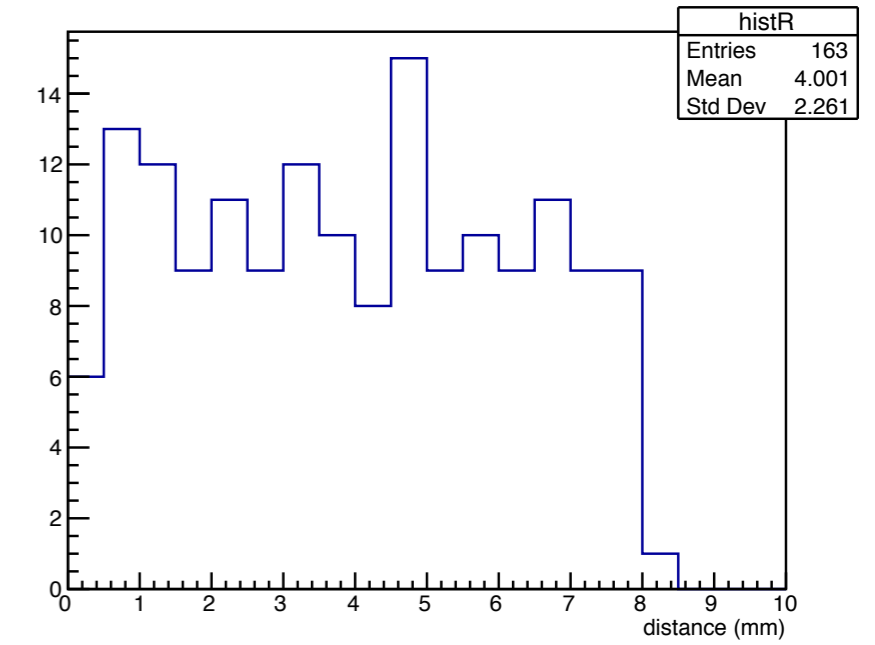
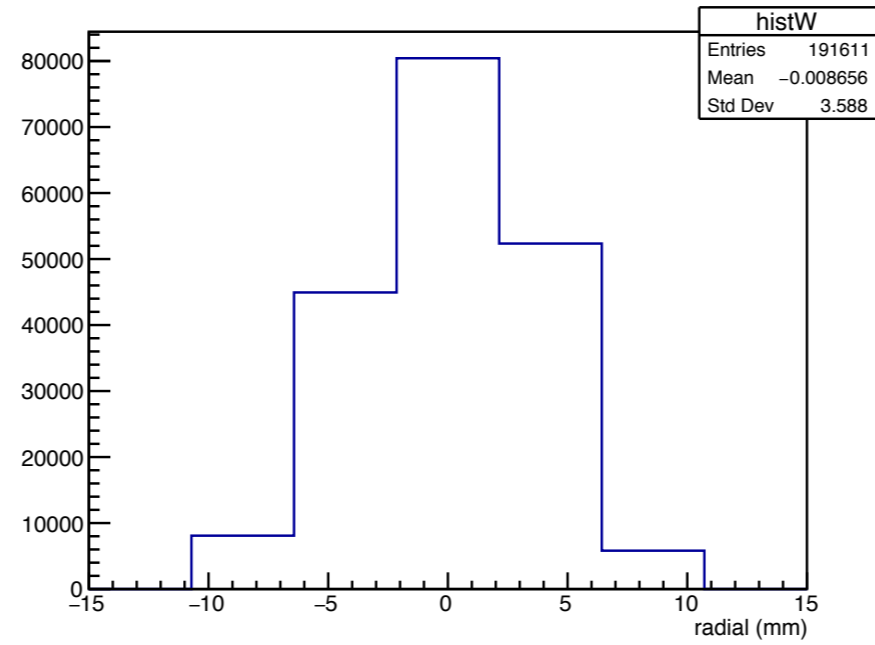
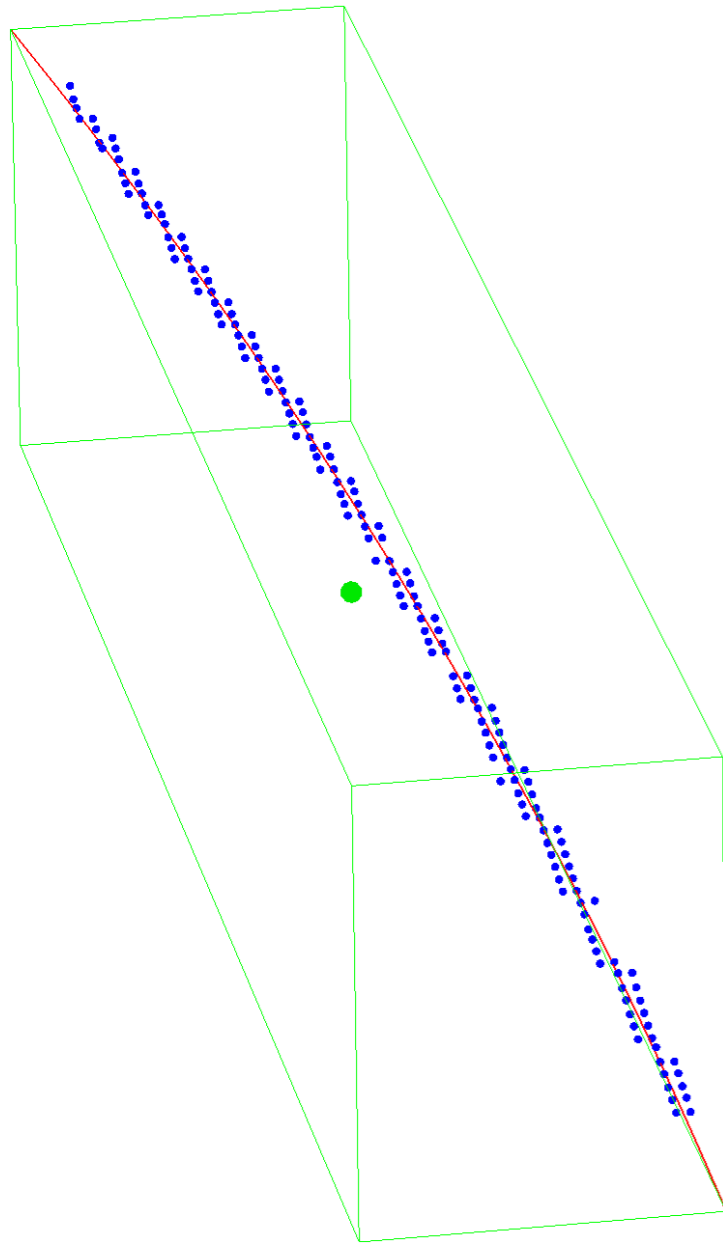


- Map space by straightening curled space : l-axis(helix line) becomes straight line.
 $(x, y, z) \rightarrow (r, t, l)$
- Origin in the mapped space is sitting on the l-axis, where α -angle becomes 0.
- Plane defined by r and t is flat in mapped space but not in real space which tells [shortest distance from point to helix] is not same as [shortest distance from point to line in mapped space].

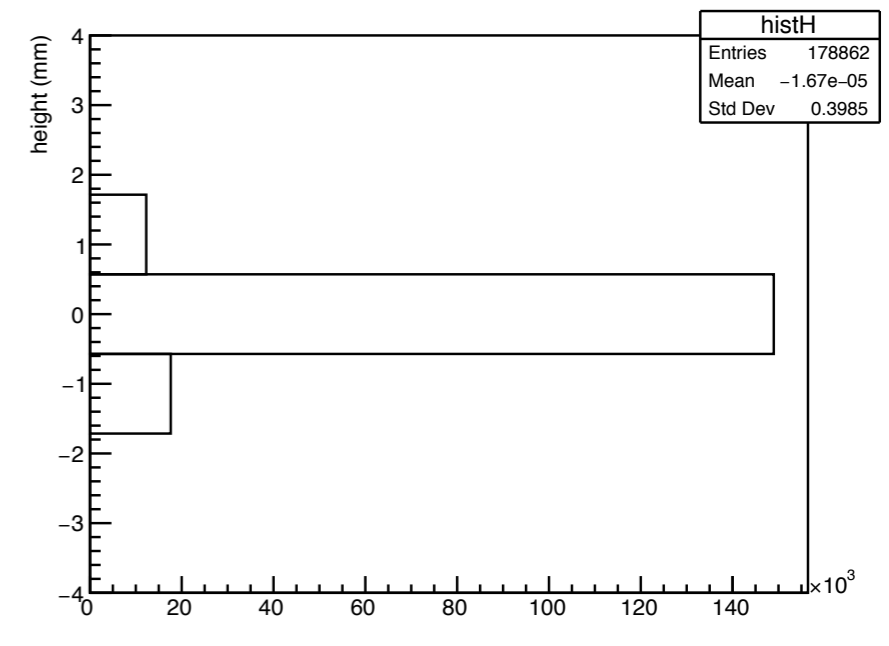
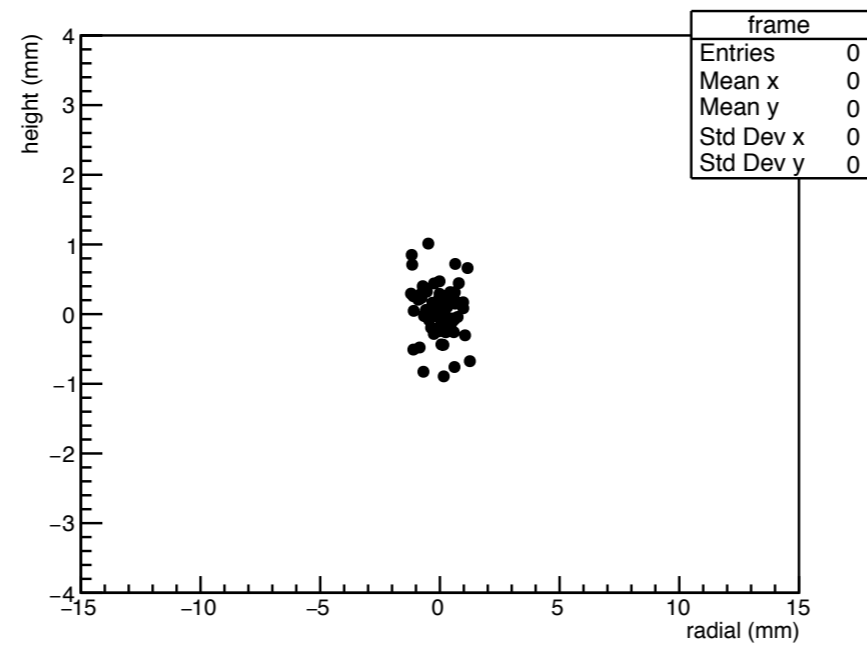
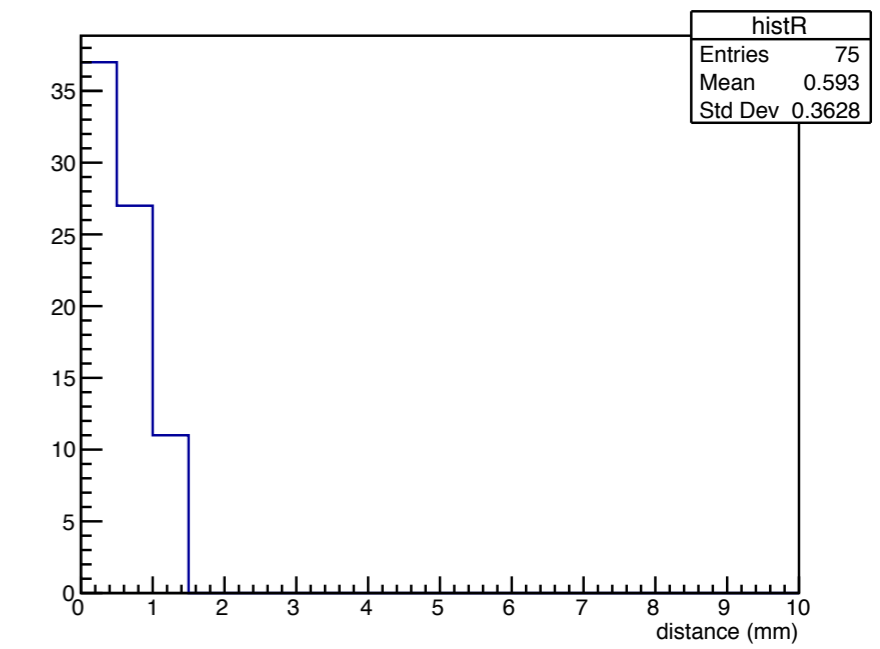
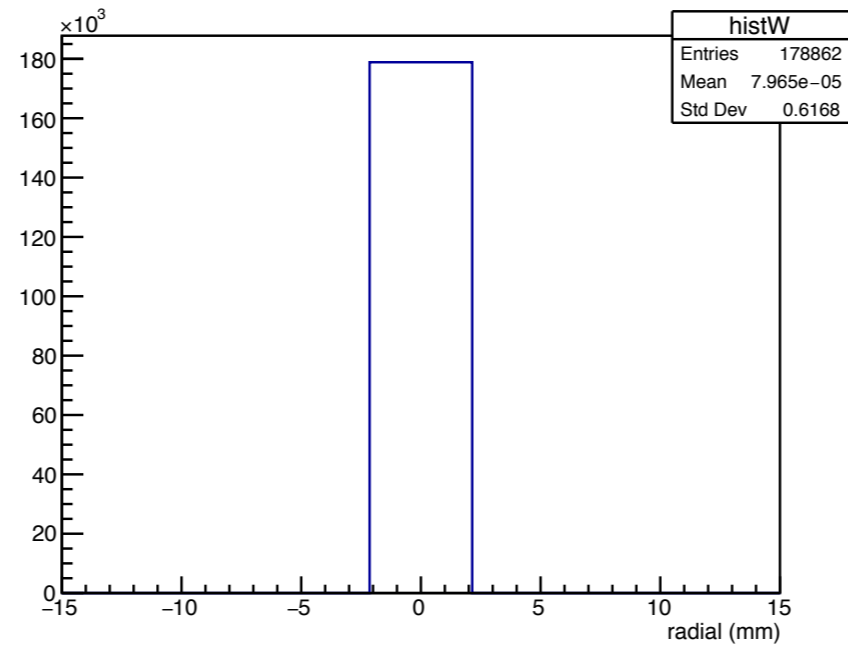
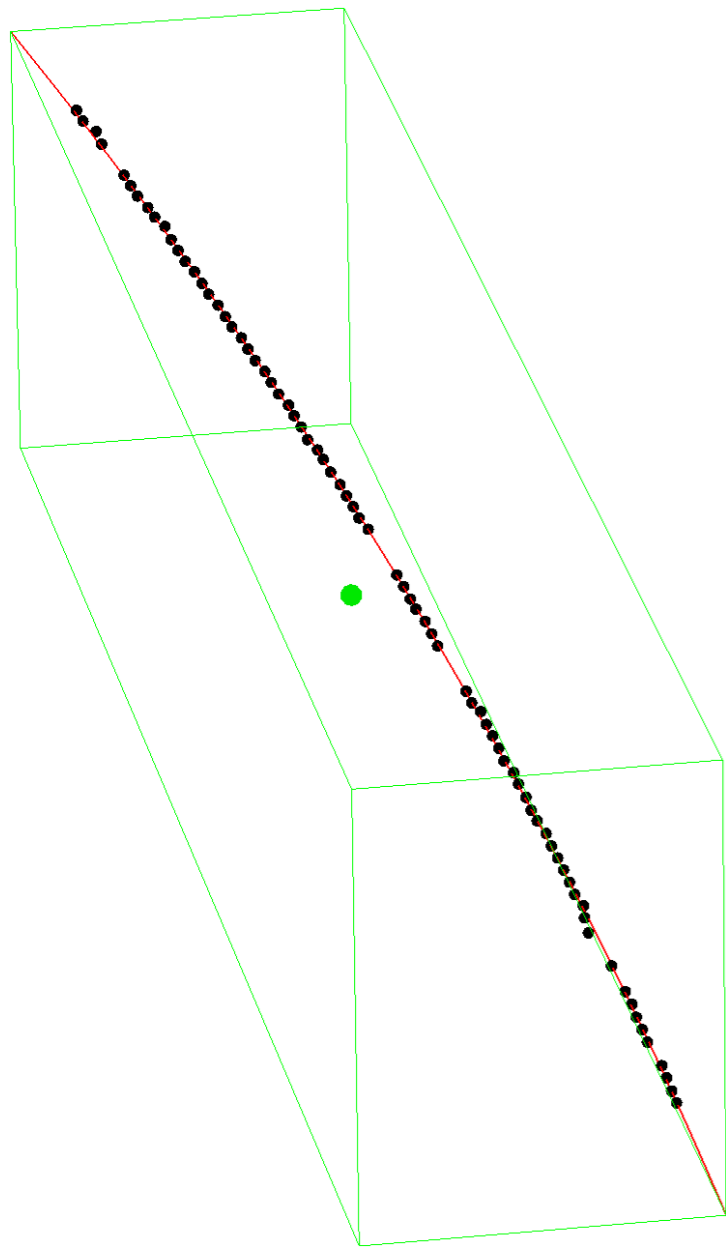


- Advantage by using position of point in new system (r, t, ℓ) is 1) distance in width-direction(r), 2) distance in height direction(t) and 3) length along the track(ℓ).
- It is possible to use this mapping instead of calculating [distance from point to helix] because **hit-track correlation cut parameters are self-updated from mapped system** which makes no difference in track finding.

Hit Map Quality Check

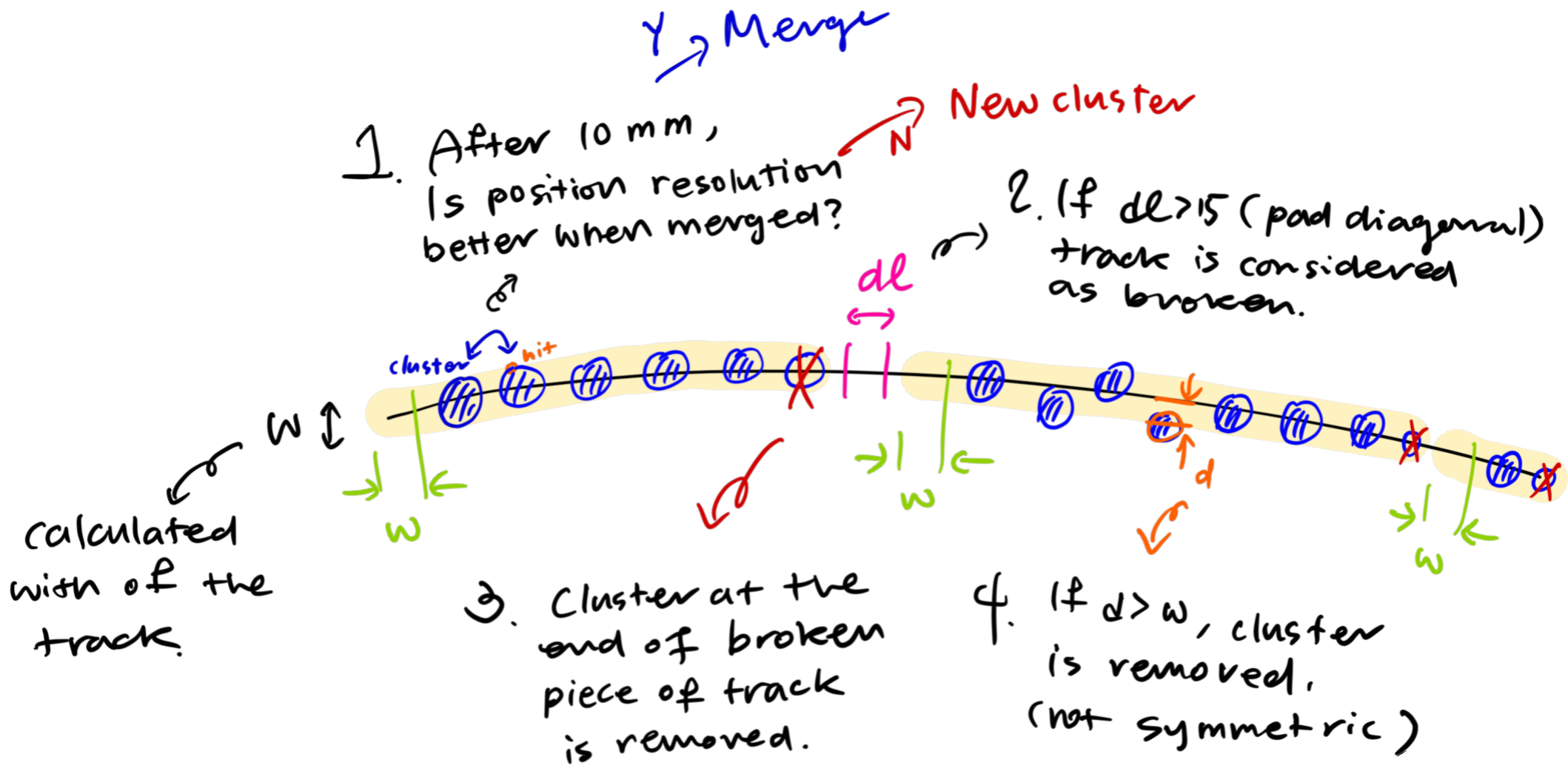


Hit-Cluster Map Quality Check

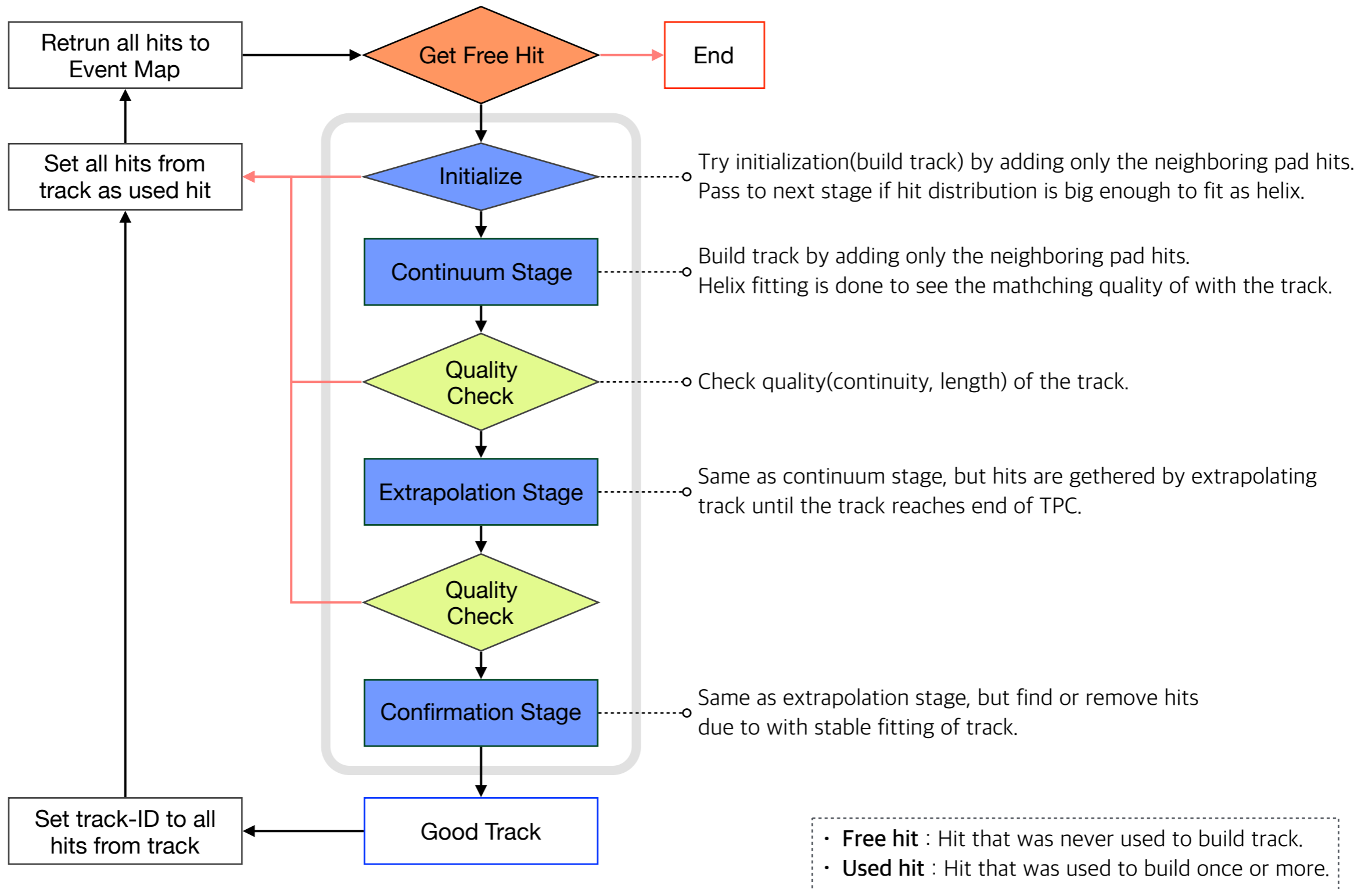


Helix Tracking

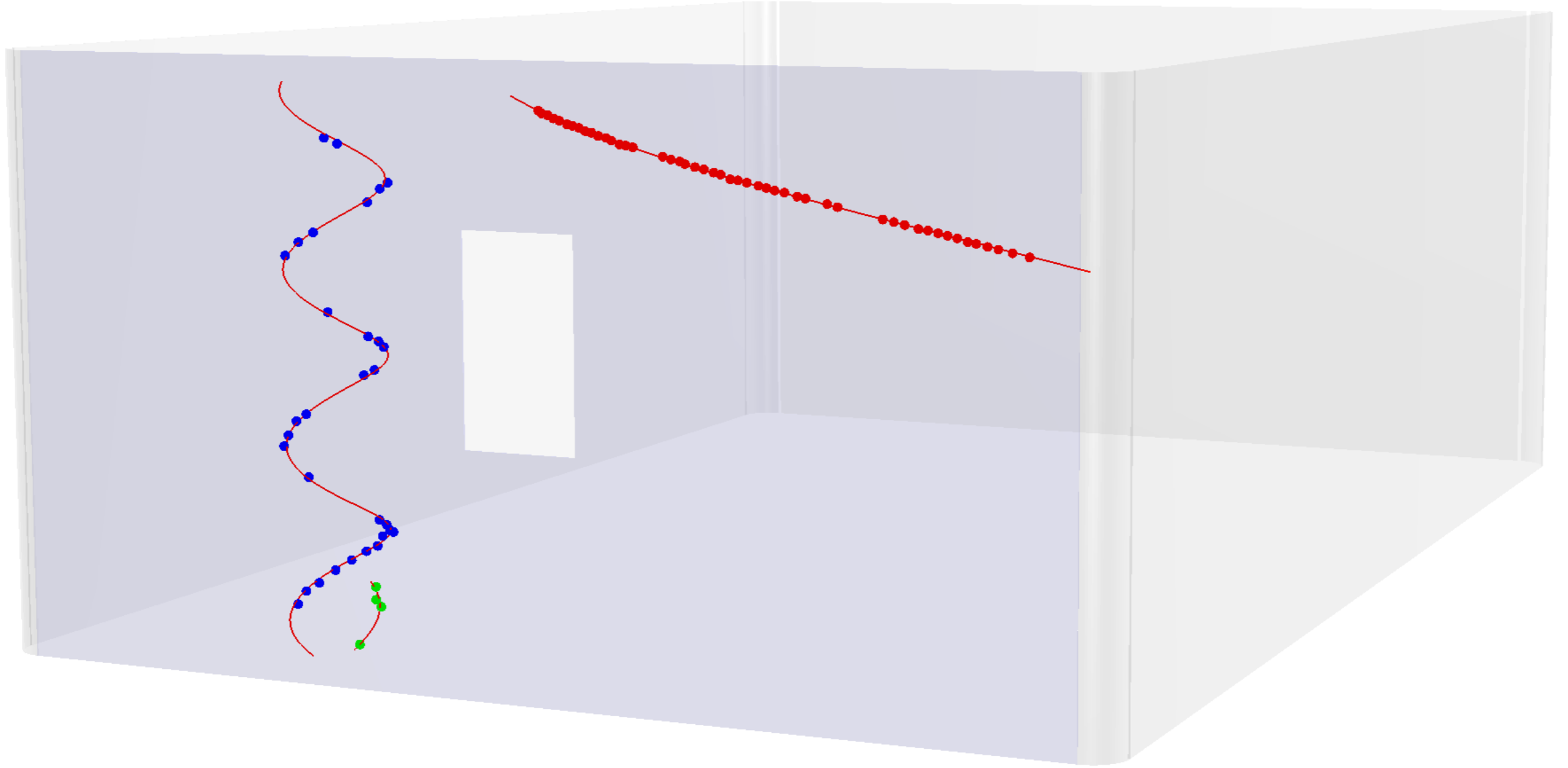
Hit-Clustering



Track Finding Algorithm



Helix!



Summary

- New tracking is developed and being tested for first release.
- New tracking has advantage in
 - ☑ Full control of the code.
 - ☑ Build full track one by one.
 - ☑ Helix to straight line map.
 - ☑ Use advantage of width of the track coming from electron dispersion.
 - ☑ Use self-update parameters.
 - Riemann sphere position and radius.
 - Proximity cut.
 - ☑ Clustering for Genfit.
- We can find helix.